Annika Thomas

Education	 Massachusetts Institute of Technology, Cambridge, MA Ph.D. Student, Mechanical Engineering Major in Robotics; Minor in Space Systems Advisor: Prof. Jonathan P. How S.M. in Mechanical Engineering Advisors: Prof. David Trumper and Prof. Kerri Caboy 	September 2021 - Present			
	Awards: Brookfield Design Fellowship, Martin Design Fellow	vship, NSF GRFP Fellowship			
	Columbia Engineering, New York, NYSeptember 2019 - MB.S. in Mechanical Engineering Awards: Distinguished Undergraduate Researcher, Dean's AwardSeptember 2019 - M				
	The College of Idaho , Caldwell, ID B.S. in Mathematics and Physics Minors in Spanish and Psychology Awards: Gipson Fellowship, Athletic Scholarship, Dean's Aw	September 2016 - May 2019 rard			
PUBLICATIONS	 SOS-Match: Segmentation for Open-Set Robust Correspondence Search and Robot Localiza- tion in Unstructured Environments. Annika Thomas*, Jouko Kinnari*, Parker C. Lusk, Kota Kondo, Jonathan P. How. International Conference on Intelligent Robots and Systems (IROS), 2024. 				
	 [2] PUMA: Fully Decentralized Uncertainty-aware Multiagent Trajectory Planner with Real-time Image Segmentation-based Frame Alignment. Kota Kondo, Claudius T. Tewari, Mason B. Peterson, Annika Thomas, Jouko Kinnari, Andrea Tagliabue, Jonathan P. How. <i>International Conference on Robotics and Automation (ICRA)</i>, 2024. 				
	 [3] Global Localization in Unstructured Environments Using Semantic Object Maps Built from Various Viewpoints. Jacqueline Ankenbauer, Parker C. Lusk, Annika Thomas, Jonathan P. How <i>International Conference on Intelligent Robots and Systems (IROS)</i>, 2023. Finalist for Best Paper in Safety, Security and Rescue Robotics. 				
	[4] Protecting Satellites in Low Earth Orbit: An Overview of Hazards and Policy Solutions. Annika Thomas*, Dansil Green*, Kristen Ammons, Laman Jalil, Joe Kusters, Kerri Cahoy Massachusetts Institute of Technology Science Policy Review, Volume IV, 2023.				
	 [5] Innovative Structural and Mechanical Satellite Systems. Annika Thomas. S.M. of Mechanical Engineering at Massachusetts Institute of Technology Thesis, 2023. 				
	 [6] The AEROS Mission: Characterizing Multi-Spectral Oce Satellite Connectivity. Cadence Payne, Pedro Miguel da Silva Pinto, Madeline Lou <i>MIT Portugal Program Conference</i>, 2023. 	an Measurements through Small			
	[7] Introducing Experimental Design to Promote Active Learnin Yevgeniy Yesilevskiy, Annika Thomas , Jessica Oehrlein, M <i>American Society for Engineering Education</i> , 2022.	ng. Ielissa Wright, Michael Tarnow.			

PUBLICATIONS BEFORE PH.D.	[8]	Real-time Estimation of Electron Dynamics in Hall Effect Thrusters using an Extended Kalman Filter. Christine Greve, Annika Thomas , Manoranjan Majji, Kentaro Hara.
		AIAA Propulsion and Energy Forum, 2020.
	[9]	Real-time Estimation of Low-Temperature Electron Dynamics. Annika Thomas, Christine Greve, Kentaro Hara. <i>Stanford SURF Lightning Talks</i> , 2020.
	[10]	Searching for Evidence of Dark Matter Interaction in Olivine. Annika Thomas, Ethan Brown, Morgan Schaller, Kelly Odgers, M. David Frey. <i>Rensselaer Polytechnic Institute Summer Research Symposium</i> , 2019.
	[11]	Investigating Bubble-Gas Clump Association to Understand the Conditions of Massive Star Formation Annika Thomas , Katie Devine. <i>College of Idaho Student Research Conference</i> , 2019.
	[12]	Magnetomechanics of Magnetic Shape Memory Micropumps. Annika Thomas, Sierra Sandison, Andrew Armstrong, Peter Mullner. Idaho Conference on Undergraduate Research; NSF Research Experience for Undergraduates Symposium, 2018.
	[13]	Harmonics of Hula-Hoop Hypocycloid Motion. Annika Thomas, Zoe Hern, Jim Dull. <i>College of Idaho Student Research Conference</i> , 2018.
	[14]	Imaging M33: Astronomy, Optics, and Electronics. Annika Thomas , Heidi Waterman, Tyler Truksa, Christian Jensen, Natash Dacic, Joe Daglen, Jim Dull. <i>College of Idaho Student Research Conference</i> , 2018.
	[15]	Visually Classifying Yellowballs to Understand their Role in Star Formation. Annika Thomas, Katie Devine. College of Idaho Student Research Conference, 2018.
	[16]	Developing Diagnostics for Sugar Beet Powdery Mildew. Annika Thomas. British Society for Plant Pathology Newsletter, 2018.

PREPRINTS[17]ROMAN: Open-Set Object Map Alignment for View-Invariant Global Localization.
Mason B. Peterson, Yi Xuan Jia, Yulun Tian, Annika Thomas and Jonathan P. How.
Arxiv Preprint, 2024.

RESEARCH MIT Aerospace Controls Laboratory

EXPERIENCE *Ph.D. Student (Supervisor: Jonathan P. How)*

Worked on global localization in unstructured environments from aerial and ground viewpoints [3], leveraged segmentation and language modeling for mapping and localization in open-set settings [4][17], incorporated uncertainty in multiagent trajectory planning [2]. Currently developing a hierarchical SLAM system leveraging Gaussian Splatting for scene understanding.

MIT STAR Laboratory

S.M. Student (Supervisor: Kerri Cahoy)

Led mechanical design, assembly, and integration of BeaverCube2 3U CubeSat, an Earth-observing nanosatellite equipped with onboard AI for task planning, segmenting, and characterizing satellite imagery with machine learning to optimize downlink decisions [5], and analyzed thermal and structural functional requirements of BeaverCube2 and AEROS [5][6].

May 2023-Present, Cambirdge, MA

Jun 2022-May 2023, Cambridge, MA

S.M. Student (Supervisor: David Trumper)
Modeled and designed feedback control system for suspension of a novel magnetically-levitated
reaction sphere for satellite attitude control [5].

Jan 2021-Jan 2022, New York, NY Research Assistant (Supervisor: Yevgeniy Yesilevskiy) Redesigned the mechanical engineering lab course, MECE E3018, at Columbia University to promote active learning [7].

Stanford Plasma Dynamics Modeling Laboratory

Visiting Researcher (Supervisor: Kentaro Hara) Predicted plasma flow in spacecraft propulsion systems using extended Kalman filtering [8][9].

Rensselaer Polytechnic Institute Brown Research Group May-Oct 2019, Troy, NY Visiting Researcher, NSF REU (Supervisors: Ethan Brown and Morgan Schaller) Designed an indirect detection technique for weakly interacting massive particle dark matter [10].

Boise State University Magnetic Materials Laboratory

Visiting Researcher, NSF REU (Supervisor: Peter Mullner) Designed using SolidWorks and machined biomechanical micropumps, including characterization tests and a user interface to control flow rate [12].

College of Idaho Star Formation Research Lab Independent Study (Supervisor: Katie Devine) Visually classified Yellowballs to refine their radius measurements and performed statistical analysis of regression [15].

College of Idaho Observational Astronomy Dec 2017-May 2018, Mayhill, NM; Caldwell, ID Independent Study and Field Work (Supervisors: Joe Daglen and Jim Dull) Collected and analyzed exoplanet data and performed specroscopy, operated telescopes, imaged M33 galaxy [14].

INDUSTRY	MIT Lincoln Laboratory, Group 76 May-Aug 2022, Le	xington, MA		
Experience	Engineering Intern, Control and Autonomous Systems			
	Implemented object detection, obstacle avoidance and trajectory planning algorithms for autonomous			
	vehicles, developed a state space model of an inverted double pendulum.			
Awards	Best in Theme, Long Duration Mars Simulation at the Moon, NASA RASC-AL	2024		
	Finalist, Best Paper in Safety, Security and Rescue Robotics, IROS [3]	2023		
	GRFP Fellowship, National Science Foundation	2023		
	Outstanding GRA, MIT Fraternaties, Sororities and Independent Living Groups	2023		
	Selected from over 100 graduate residential assistants for service to the community			
	Martin Fellowship for Design, MIT	2022		
	Brookfield Fellowship, MIT	2021		
	Distinguished Tutor, Columbia Tutoring and Learning Center	2021		
	Developed teaching materials to support students from low-income backgrounds			
	John K. Mladinov Scholarship, Columbia Named Scholarships	2020; 2021		
	U.S. Bank Academic All-Conference Award, Cascade Collegiate Conference	2017-2019		
	Selected for service and academic excellence while captain of Varsity Women's Golf			
	Math and Physical Sciences Department Scholarship, College of Idaho	2017		
	Awarded to an outstanding student in the MAPS department			
	Presidential Merit Scholarship, College of Idaho	2016-2019		

MIT Precision Motion Control Laboratory

Columbia Engineering

May-Sep 2020, Palo Alto, CA

Feb-May 2019, Caldwell, ID

May-Jul 2018, Boise, ID

Aug 2021-May 2023, Cambridge, MA

TEACHING AND	Research Mentor, Polygence F	Feb 2022 - Present		
Leadership	Providing mentorship for students to pursue independently led research projects related to			
Experience	XPERIENCE robotics, Lunar architecture, machine learning and aircraft/spacecraft design.			
	Invited Lecturer, MIT First Year Graduate Seminar	Sep 2024		
	Teaching Assistant: Stochastics; Product Design (Qualifying Exams), MIT S	ep 2023-Jan 2024		
	Invited Speaker, Women in Engineering Showcase, MIT	Aug 2023		
	Presented on segmentation for robotic mapping and localization in extreme environments			
	Instructor, Beaver Works Summer Institute MIT			
	Instructor MIT Women's Technology Program MIT	June 2023		
	Instructor Summer High School Program for Engineers Columbia	May_Aug 2021		
	Taught advanced robotics and multivariable calculus to 30 students	May-Mug 2021		
Service &	NASA Lunar Autonomy Challenge, MIT Team Lead	Sep 2024-Present		
Extra-	Leading a team of 12 students to perform surface mapping, autonomous rob	otic operation, lo-		
CURRICULARS	RRICULARS calization, orientation, path planning, and object detection on the Lunar surfa			
	MIT AeroAstro Communication Lab, Fellow	May 2024-Present		
	Provide one-on-one support to undergraduate and graduate students at MIT f	for journal papers,		
	conference presentations, lab reports, research posters, theses, and job applicat	tions.		
	MIT Housing & Residential Services. Graduate Residential Assistant	Aug 2023-Present		
	NASA RASC-AL Lunar Mars Analog. MIT Operations Lead	g 2023-May 2024		
	Led integration of multi-agent robotics and AI into architecture for autonomo	us operations		
	MIT Graduate Student Council Volunteer	Aug 2021-Present		
	MIT Graduate Association of Mechanical Engineers Volunteer	Aug 2021 Present		
	Reviewer IEEE Robotics and Automation Letters (RA-L)	2024 2021 2024		
	Reviewer: IEEE International Conference on Robotics and Autonmation (ICRA)	2024		
	Invited Panelist Machanical Engineering Craduate Seminar MIT	Oct 2023		
	Invited Panelist, Beaver Works Summer Institute, MIT	June 2023		
Press &	Designing for Outer Space (MIT News)	2024		
Media	AEROS CubeSat Launches to Study Ocean Health (MIT Aero/Astro)	2024		
	AEROS CubeSat Mission presented at MIT Portugal Program (MIT Aero/As	stro) 2023		
	Living the Life I Used to Dream About (Featured at TechGirlz Conference)	2022		
	2022 - Year in Review (College of Idaho Annual Scholarship Gala)	2022		
	Prestigious Graduate Schools Await Recent Alumni (College of Idaho Newslet	(ter) 2021		
	A Laboratory Fit for Lockdown (Columbia Magazine)	2021		
	Program alumna navs it forward by helping new students learn to SURF (St	anford) 2021		
	Annika Thomas Works on Plasma Engines for Snace Propulsion (Stanford)	2021 2020		
	Finding the Way: The Thomas Tutors (College of Idaho Magazine)	2020		
Selected	MIT Perception and Localization Seminar: Open-Set Object-Based Localization	on Oct 2024		
INVITED TALKS	John F. Kennedy High School: Computer Vision in Astronomy	Oct 2024		
	TEDxBoston: Robotics and Regolith: Building Habitats from Moon Dust	July 2024		
	MIT Media Lab (Roxbury Latin): Vision in Space	June 2024		
	TEDxMIT: Collaborative Vision Systems for Space Exploration	Apr 2024		
	Universidad del Valle de Guatemala Women in Engineering Program	r		
	From Pathology to Path Planning: Exploring New Frontiers in Robotics	Apr 2024		
SKILLS	Languages English (native), Spanish (advanced)			
	Programming Python, PyTorch, C/C++, ROS, Java, Matlab, R Studio, Mathematica, HTML			
	Technical Expertise Computer Vision, SLAM, Localization, Pose Estimation, 3D Geometry, Track-			
	ing, Neural Rendering, Reconstruction, Linear Algebra, Optimization, Deep Learning			